

2017 The 3rd International Conference on Robotics and Computer Vision

ABOUT ICRCV2017

2017 The 3rd International Conference on Robotics and Computer Vision (ICRCV 2017) will be held in Nagoya, Japan during April 22-24, 2017.

ICRCV is the main annual Robotics and Computer Vision conference aimed at presenting current research being carried out. We take this opportunity of urging you to consider sharing your expertise on different aspects of Robotics and Computer Vision with your peers from around the world. We warmly welcome and encourage you to join us, share your research efforts & findings with your peers, appraise yourself with their experiences, publish your research (in both the proceedings of the respective conferences as well as the possibility of the same in SCOPUS-indexed journals too) and in the process, contribute towards advancing the state-of-the-art in the field of Robotics and Computer Vision.

We sincerely hope that armed with your support, ICRCV 2017 will be able to make a prominent mark on the global events map in the coming years. We look forward to your participation and continued engagement at future ICRCV conferences.

PUBLICATION



Journal

International Journal of Mechanical Engineering and Robotics Research (ISSN: 2278-0149)

Selected papers will be recommended to IJMERR. Indexed by: Index Corpernicus, ProQuest, UDL, Google Scholar, Open J-Gate, Scopus (since 2016) etc.

Conference Proceedings

The conference proceedings will be online and included in the major data base, such as SCOPUS, Ei.

KEYNOTE SPEAKERS

Prof. Mo El-Hawary, Electrical Engineering, Dalhousie University, Canada

Prof. Wei-Hsin Liao, The Chinese University Of Hong Kong

Dr. Ferial El-Hawary, Dalhousie U., Canada, IEEE Life Fellow

CONFERENCE VENUE

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<http://www.nitech.ac.jp/eng/about/index.html>

CALL FOR PAPER

- Evolutionary Robotics
- Distributed Sensor Networks
- Robot Surgery
- Search and Rescue Robots
- Biorobotics
- Humanoid Robotics
- Autonomous Vehicles
- Entertainment Robots
- Rehabilitation Robotics
- Micro/Nano Robotics
- Underwater Robots
- Service Robotics
- Sensors and Early Vision

- Shape Representation
- Physics-based Modeling
- Object Recognition
- Image-based Modeling
- Illumination and Reflectance Modeling
- Video Analysis and Event Recognition
- Face and Gesture
- Statistical Methods and Learning
- Vision for Robots
- Performance Evaluation
- Medical Image Analysis
- Image and Video Retrieval
- Color and Texture
- Segmentation and Grouping
- Motion and Tracking
- Stereo and Structure from Motion

IMPORTANT DATE

Submission deadline: December 30, 2016

Notification Date: January 20, 2017

Registration Deadline: February 10, 2017

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